

# Arav Bhargava

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## EDUCATION

### HARVARD COLLEGE

B.S. in Electrical Engineering. Minor in Computer Science. **GPA:** 3.97

Cambridge, MA

May 2028

**Relevant Coursework:** Computer-Aided Machine Design; Vector Calculus; Biomechanics and Assistive Robotics (Spring 2026)

**Student Groups:** Harvard Ventures (Board), The Bottom Line (Host), Harvard Biotech Club, Harvard GAMI, Club Swimming

**Awards:** Regeneron Science Talent Search Top 40, VEX Robotics World Championship Finalist; Capital Emmy Winner

## TECHNICAL SKILLS

**Skills:** Robotics & Embedded Systems (Python, Embedded C/C++), Actuation & Control (servo/DC/BLDC integration, PID/trajectory basics), Perception (OpenCV, OpenPIV), ML for Robotics (PyTorch, TensorFlow, data pipelines with Pandas), Electronics (circuit design/analysis, PCB design in KiCad), Mechanical Design (SolidWorks, Fusion 360, FEA, FDM 3D printing)

## PROFESSIONAL EXPERIENCE

### MOBILIS

Cambridge, MA

**Founder, Accessible Prostheses for Developing Countries**

September 2021-Present

- Designed and patented a <\$40, accessible, size-adjustable prosthesis for upper-limb amputees in developing regions
- Rapid-prototyped and iterated 300+ designs with end-users and clinicians (Fusion 360, FDM 3D printing, FEA)
- Engineered novel BOA tensioning system, pseudo-silicone interior liner, and adapted mechanical hook/hand control
- Validated design through bench testing and user trials to meet ISO socket standards, achieving comfort ratings surpassing traditional prosthetics at <1% of cost; deploying in Ukraine and India (Dec 2025).
- Launched “The Prosthetic Experience” podcast (NPR National award-winner; 10,000+ Listens)
- Awarded Regeneron STS National Top 40 (\$27,000); featured on *ABC News*, *Scripps News*, *3Dprint.com*, *The 74*

### HARVARD MICROROBOTICS LABORATORY

Cambridge, MA

**Researcher, Selected as a PRISE Fellow to advance microrobotic applications**

May 2025-Present

- Developed and open-sourced a Low-Turbulence Vertical Wind Tunnel for Microrobotic Insect Flight Testing with 44% reduction in turbulence; design to be used by MIT and Berkeley labs (KiCad, Fusion 360, C++)
- Designed a computer vision program to analyze wind particle flow and perform PIV analysis of microrobot aerodynamics (Python, OpenCV, OpenPIV)

### CODA LLC

McLean, VA

**Summer Associate, Leading Digital Provider to the Built Environment**

June-August 2023

- Helped develop a new ML-driven approach to detect expensive errors in construction design (Revit, Dynamo)
- Wrote 3D model design check scripts with Dynamo to create an egress path program to sell to OSHA

## FEATURED PROJECTS AND ADDITIONAL EXPERIENCE

### REAL-TIME TRAINABLE BIONIC ARM FOR IMPROVING ROBOTIC MODELS (Project)

April 2025

- Engineered an EMG-based embedded control system for a multi-DOF bionic arm robot, with analog filtering (20–500 Hz) and noise cancellation, achieving real-time, low-latency control and reducing model training time to <2 minutes.
- Implemented a KNN classifier in C++ to control multi-servo tendon actuation; validated responsive hand motion via oscilloscope and EMG trials across multiple users

### SO101 ROBOT ARM - TELEOP, VISION DATASET, AND POLICY TRAINING (Project)

January 2026-Present

- Built an SO101 arm manipulation pipeline in Python for teleoperation and control, with synchronized logging of observations and actions to create demonstration datasets for pick-and-place.
- Added vision-based perception for pose estimation and ran baseline policy training on collected demos, tracking success rate, and common failure modes across different object positions and lighting conditions.

### VEX ROBOTICS - POTOMAC ROBOTICS TEAM (Engineering Lead)

September 2020-June 2024

- Engineered, fabricated, and coded competition robots (VEX), including mechatronic subsystems, sensors & actuators, and autonomous control for global-level robotics competitions.
- Implemented pneumatic-controlled transmission systems; utilized C++ to create autonomous programs

### HARVARD VENTURES (Board)

January 2025-Present

- Co-hosting and directing Harvard Ventures podcast “The Bottom Line” end-to-end
- Interviewing Fortune 500 founders on building extraordinary ventures (15,000+ listens)